

Main Definition

“*What is entropy?*”... What entropy definition can give a unified picture of the 2nd Law across non-/equilibrium, open/isolated, pure/mixed, classical/quantum systems?

The idea of this paper [1] is to combine von Neumann’s “macroscopic entropy” [2] (i.e. “observational entropy” [3]) and Jaynes’ “maximum entropy principle” [4] into a single coarse-grained entropy definition uniting nearly all entropies in physics.

Informational Form

Definition. The entropy of state ρ , coarse-grained by measurement M , with prior τ , is

$$S_M^\tau(\rho) = S(\tau) - D_M(\rho\|\tau).$$

This is missing information given both measured info and constraint info.

Prior = MaxEnt state for constraints on the system.

Measured RE: $D_M(\rho\|\tau) \equiv D(p\|q)$ where $p_x = \text{Tr}(M_x\rho)$ and $q_x = \text{Tr}(M_x\tau)$.

The definition derives from the principle “entropy = missing information”, or

$$S = I_{\text{tot}} - I,$$

which for Shannon $H(p)$, von Neumann $S(\rho)$, and the standard OE $S_M(\rho)$, is stated

$$\begin{aligned} H(p) &= \log N - D(p\|\mathbb{1}/N) \\ S(\rho) &= \log d - D(\rho\|\mathbb{1}/d) \\ S_M(\rho) &= \log d - D_M(\rho\|\mathbb{1}/d). \end{aligned}$$

These implicitly assume prior ignorance, with $\mathbb{1}/d$ appearing as the informational prior. The new definition assumes prior knowledge of a linear constraint such as $\langle H \rangle = E$, with the maximum entropy state τ taken as the prior.

vN’s macroscopic entropy (=traditional OE): $S_M(\rho) = \log d - D_M(\rho\|\mathbb{1}/d)$.

Stat Mech Form

Equivalent definitions. The above entropy is equivalent to

$$S_M^\tau(\rho) = - \sum_x p_x \log \frac{p_x}{V_x},$$

which is also the Shannon plus mean Boltzmann entropy

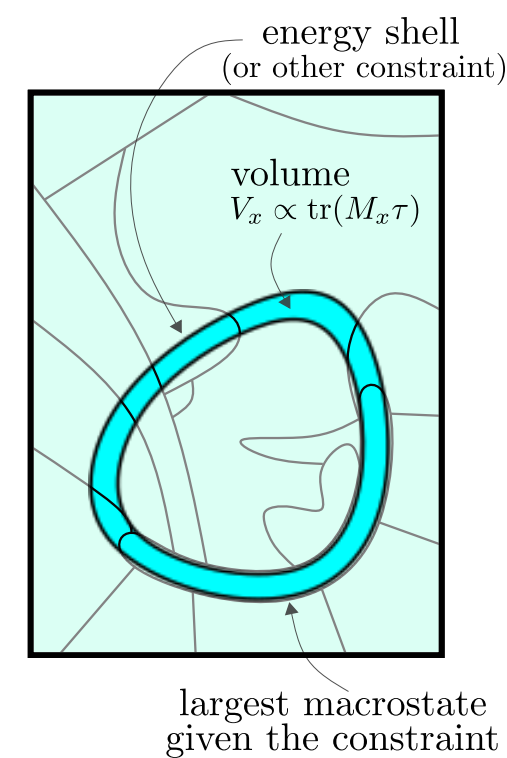
$$S_M^\tau(\rho) = H(p) + \sum_x p_x \log V_x,$$

combining “which macrostate” uncertainty and “which microstate given macrostate” uncertainty.

Macrostate probabilities (actual and prior): $p_x = \text{Tr}(M_x\rho)$ and $q_x = \text{Tr}(M_x\tau)$.

Effective dimension of set of constrained states: $d_{\text{eff}} = e^{S(\tau)}$.

Macrostate volumes: $V_x = q_x d_{\text{eff}}$.



Uniform (Prior: $\tau = \mathbb{1}/d$. Constraint = trivial. Vols: $V_x = \text{Tr}(M_x)$.):

$$S_M^\tau(\rho) = \log d - D_M(\rho\|\mathbb{1}/d).$$

Canonical (Prior: $\tau = e^{-\beta H}/Z$. Constraint $\langle H \rangle = E$. Vols: $\text{Tr}(M_x e^{-\beta(H-E)})$.):

$$S_M^\tau(\rho) = \beta E + \log Z - D_M(\rho\|e^{-\beta H}/Z).$$

Microcanonical (Prior: $\tau = \Pi/W$. Constraint $\rho \in \Pi$. Vols: $V_x = \text{Tr}(M_x \Pi)$.):

$$S_M^\tau(\rho) = \log W - D_M(\rho\|\Pi/W).$$

...textbook EQ entropies become dynamical non-EQ maxima.

Entropy increase: system finds *most likely macrostates given the constraints*.

Observed versus Inherent Information

For states ρ obeying the constraint $S(\rho; \tau) \leq S(\tau)$ (= arbitrary linear constraint),

$$S_M^\tau(\rho) \geq S(\rho).$$

No observer can extract more information than what is inherently available in the state.

Uniting the Entropy Zoo: Special Cases and Limits

Nearly all commonly used physical entropies derive from $S_M^\tau(\rho)$ as special cases and limits.

Fundamental Limits

- von Neumann (or classical Gibbs) entropy $S(\rho)$**
The lower bound $S_M^\tau(\rho) \geq S(\rho)$.
Optimal M case: $\min_M S_M(\rho) = S(\rho)$.
(Bound assumes constraint: false info is unbounded.)
- Jaynes max entropy $S(\tau)$**
The upper bound $S(\tau) \geq S_M^\tau(\rho)$.
The equilibrium value.
The case of trivial $M = (\mathbb{1})$.
- Boltzmann entropy $\log V_x$**
The case of a definite macrostate (only one nonzero p_x).
In itself still a generalization due to generalized V_x .
A contribution to the total (mean Boltzmann term).
- Observable Shannon entropy $H_M(\rho)$**
The case of equal prior probabilities ($V_x = \text{const}$), as for $M = (|x\rangle\langle x|)_x$ with $\tau = \mathbb{1}/d$.
A contribution to the total (Shannon term).
- Observational entropy (traditional def) $S_M(\rho)$**
The case $\tau = \mathbb{1}/d$ (uniform prior, trivial constraint).

Entropy Production

- Entropy production (general)**

Large class of methods, often captured by

$$\Delta S_M^\tau = S_M^\tau(\rho(t)) - S_M^\tau(\rho(0))$$

with time-dependent M, τ, ρ .

- Entropy production (Quantum Thermo eg Potts 2019)**

System \otimes Bath

$\tau(t) = \mathbb{1}_S \otimes e^{-\beta(t)H_B}$ is bath energy constraint $\langle H_B \rangle = E_B(t)$.

$M(t) = M_S(t) \otimes \mathbb{1}_B$ are optimal measurements on system.

With $T_B = \beta^{-1}$ one finds

$$\Delta S_M^\tau = \Delta S(\rho_S) + \int_0^t \frac{dE_B(t')}{T_B(t')}$$

For decorrelated thermal $\rho(0)$ this equals the usual RE form, and is ≥ 0 .

Usual RE form is EP = $D(\rho(t)\|\rho_S(t) \otimes \tau_B(t))$.

- Entropy production (Stochastic thermodynamics)**

System \otimes Environment.

$\tau = \Pi_E/W_E$ global microcanonical energy shell.

$M = \Pi_S \otimes \mathbb{1}$ projective measurement on system.

Defining a bunch of fancy things shows

$$\Delta S_M^\tau(\rho) = -\beta \Delta \langle E_x \rangle + \Delta \langle S_x - \log p_x \rangle$$

which is stochastic EP as in (11) of Seifert 2017.

S_x = intrinsic mesostate entropy

E_x = mesostate energy

β = environment temp

Local Detailed Balance

- 2nd law of stochastic thermodynamics**

If $dp_x/dt = \sum_{x'} R_{xx'} p_{x'}$ with LDB $R_{xx'}/R_{x'x} = q_x/q_{x'}$, then

$$\frac{d}{dt} S_M^\tau(\rho) = \sum_{x,x'} R_{xx'} p_{x'} \log \frac{R_{xx'} p_{x'}}{R_{x'x} p_x} \geq 0.$$

Clausius Relations

- Clausius inequalities**

See paper for how relations like

$$\Delta S_M^\tau(\rho) = \int \frac{dE_A}{T_A} + \int \frac{dE_B}{T_B} \geq 0$$

are derived in either canonical or microcanonical form, and conditions where ≥ 0 is guaranteed or highly probable.

More Particular Limits

- Diagonal entropy**
Boring version: The case $M = (|E\rangle\langle E|)_E$ with $\tau \propto \mathbb{1}$.
Cool version: Equilibrium entropy $S(\bar{p})$ associated with the tightest possible stationary constraint $\tau = \bar{p}$.
(Note: constant in isolated systems.)

- Entanglement entropy**

Minimum for local M on entangled subsystems,

$$S_{\text{ent}}(\psi_{AB}) = \inf_{M_A, M_B} S_{M_A \otimes M_B}(\psi_{AB}).$$

Compare global minimum $S(\rho) = \min_M S_M(\rho)$.

- Wehrl entropy (Wehrl 1979)**

The case of POVM $M = \left(\frac{|z\rangle\langle z|}{\pi}\right)_{z \in \mathbb{C}^n}$, where $|z\rangle$ are the overcomplete basis of coherent states, with $\tau \propto \mathbb{1}$, so

$$S_M^\tau(\rho) = -\frac{1}{\pi} \int dz Q \log Q, \quad Q(z) = \langle z|\rho|z\rangle.$$

- Free energies**

Can arise in many ways, see paper.

- Rényi, Tsallis, and related entropies**

Replace D_M by generalized divergence. For Rényi,

$$S_{M,\alpha}^\tau(\rho) = S(\tau) - D_M^\alpha(\rho\|\tau) = -\log \langle (p_x/V_x) \rangle_{p_x}^{1/\alpha}$$

where $\alpha = 1 + s$, measures moments of prob-to-vol ratio.

- Dynamical canonical entropy**

The case $\tau(t) \propto \tau_A(t) \otimes \tau_B(t)$ with $\tau_A(t) \propto e^{-\beta_A(t)H_A}$, and so on, for local energy constraint in subsystems.

- HEP coarse-/fine-grained entropies**

The cases $S(\tau)$ and $S(\rho)$, respectively.

Historical H-theorems

- Boltzmann’s H-theorems (Boltzmann 1872)**
 $\tau = e^{-\beta H}/Z$ canonical prior (average energy conservation).
 $M_{P(E)}$ measures distribution of 1-particle energies.
 $M_{P(\vec{x}, \vec{p})}$ measures distribution over 1-particle phase space.

$$S_{M_{P(E)}}^\tau(\rho) = C' - n \int P(E) \log \frac{P(E)}{E^{-\frac{n}{2}+1}} dE$$

$$S_{M_{P(\vec{x}, \vec{p})}}^\tau(\rho) = C - n \int P(\vec{x}, \vec{p}) \log P(\vec{x}, \vec{p}) d\vec{x} d\vec{p}$$

Therefore Boltzmann’s H-theorems are equivalent to

$$\frac{d}{dt} S_M^\tau(\rho) \geq 0.$$

(Strict non-negativity is due to his simplifying assumptions.)

- Gibbs H-theorem (XII of Gibbs 1902)**

Uniform prior $\tau \propto \mathbb{1}$.

M cuts the full n -particle phase space into finite cells.

Equivalent to

$$S_M(\rho_0) \leq S_M(\rho_{t \rightarrow \infty})$$

in notation of (66-67) of Ehrenfest 1912.

- von Neumann’s quantum H-theorem (vN 1929)**
 $\tau = \sum_E \text{Tr}(\rho \Pi_E) \frac{\Pi_E}{\text{Tr} \Pi_E}$ mixture of microcanonical shells (a coarse version of \bar{p}).

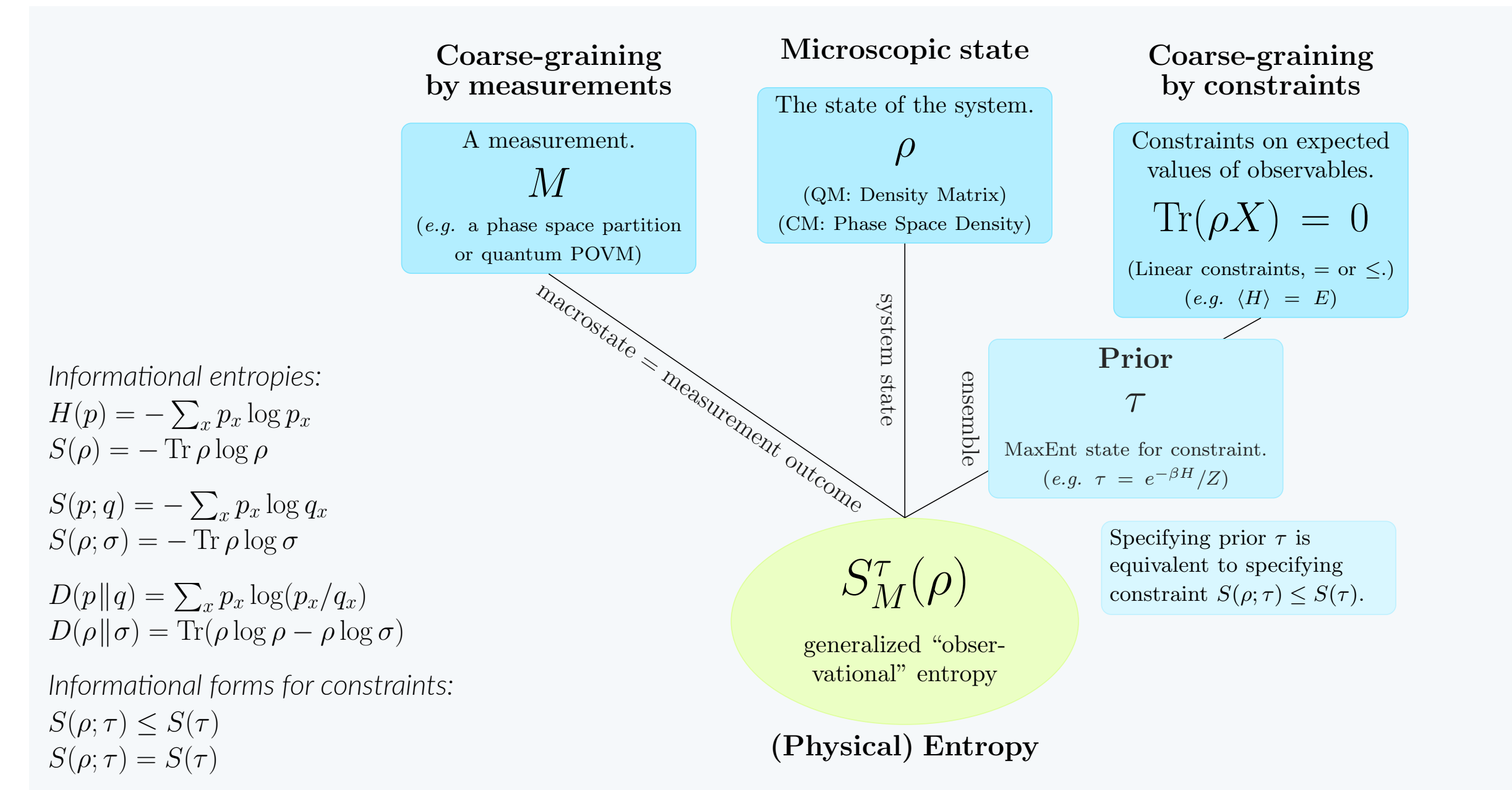
M = anything coarser than “quantum phase cells” (ie. coarser than some M' that commutes with the Π_E)

What vN calls $S(\mathbf{U}_\psi) - S(\psi)$ is equal to our $D_M(\rho\|\tau)$.

Thus von Neumann’s H-theorem is of the form

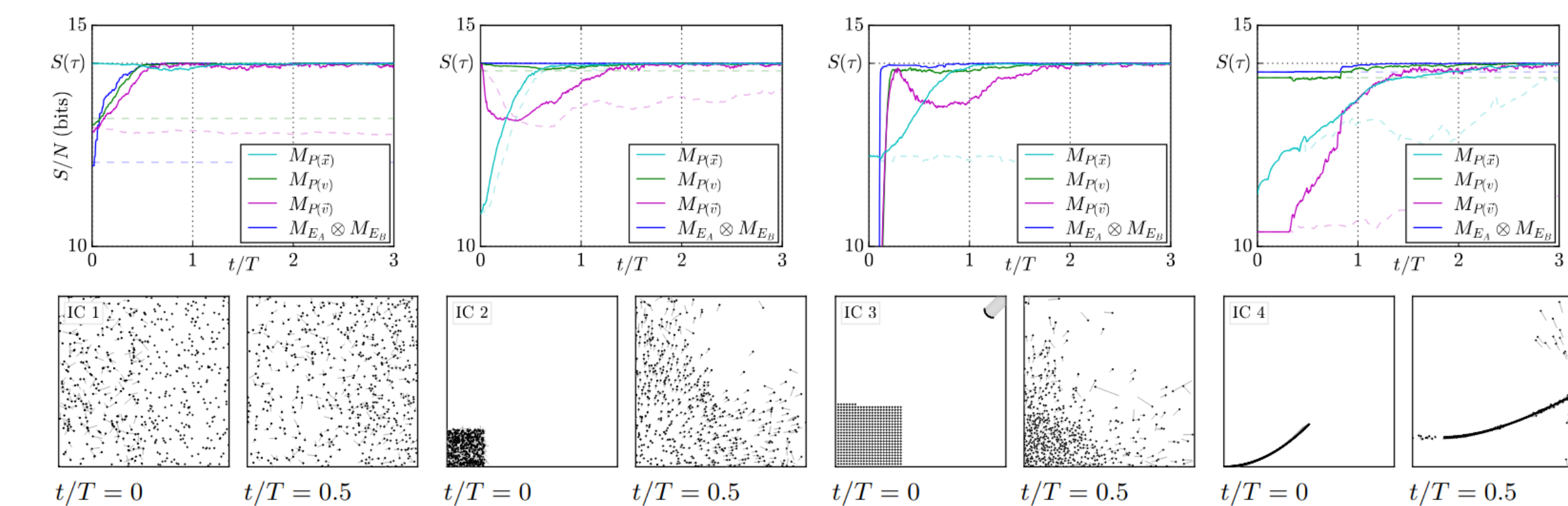
$$S(\tau) - \overline{S_M^\tau(\rho)} \leq \epsilon$$

of same form as our main equilibration theorems (Sec. VII).



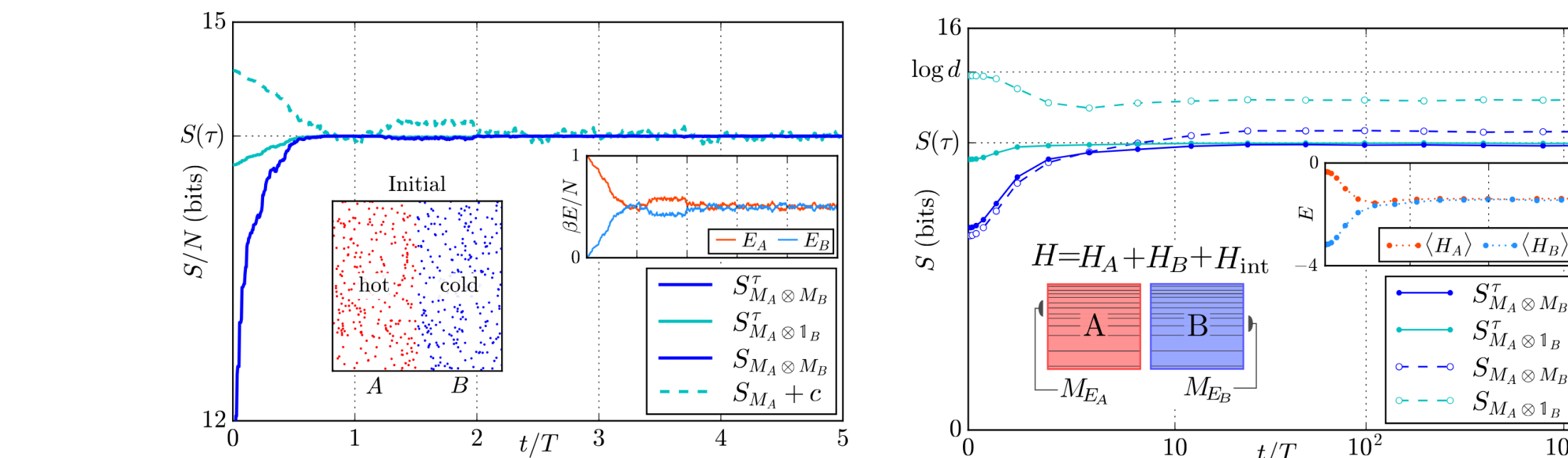
Physical Examples

Different M capture different ways a state can be low entropy!



(Depicted: Prior $\tau = e^{-\beta H}/Z$, Measurement M = spatial, velocity, speeds, or thermodynamic.)

Heat exchange in a classical hard sphere gas versus quantum random matrix model.



(Depicted: Prior $\tau = e^{-\beta H}/Z$, Measurement M = coarse local energy measurements.)

Standard thermo = energy measurements/constraints on weakly coupled subsystems. Many second laws are important: mixing the pancakes versus letting them cool.

Second Laws and Thermodynamics

In the paper we show various entropy increase theorems that can be rigorously proved for $S_M^\tau(\rho)$ in both isolated and open systems, and discuss how these entropy increase theorems connect to thermodynamics. See paper.

References

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